

PDAB SERIES

LINEAR SERVO MOTOR ACTUATOR
IRONLESS

PBA
SYSTEMS

www.pbasystems.com.sg

PART NUMBERING SYSTEM

■ Coil Assembly

PDAB- D5 - C1 - S - TM - 1.0 - FC - HC - E1.0 - O - 1600 - 00

MOTOR MODEL

D3	DX 30B
D3T	DX 30BT
D5	DX 50B
D5T	DX 50BT

COIL SIZE

C1
C2
C3
C4
C5

CONNECTION TYPE

S	Series
P	Parallel

THERMAL PROTECTION

TC*	PT 100 Sensor
TM**	Thermostat

CABLE LENGTH***

0.5	0.5m
1.0	1.0m
2.0	2.0m
3.0	3.0m
4.0	4.0m
5.0	5.0m

POWER CABLE OPTIONS

NF	No Ferrite Core (Flying Leads)
FC	Ferrite Core (Recommended)
9NF	No Ferrite Core, D Sub 9 pins Female Connector
CNF	No Ferrite Core, Circular Quick Lock 6 pins Male Connector

DESIGN VERSIONS

00	Standard
01	Customized Version
:	

EFFECTIVE STROKE (mm)

100-1600	Open Type
100-1600	Covered Type
100-1000	Bellow Type

ACTUATOR SIZE

O	Open
C	Covered
B	Bellow

ENCODER RESOLUTION

EA	Analog
E0.5	0.5 um
E1.0	1.0 um

HALL SENSOR CONNECTOR OPTIONS

H	Flying Leads (No Connector)
HC	9 pins D Sub Male Connector
CHC	5 pins Circular Quick Lock Male Connector

* TC - Sensor output to temperature controller

** TM - On/Off switch, triggers at 100°C

*** Encoder, power & hall cable

LINEAR ACTUATOR

DX B / BT

PIX / PIXA

PSM / PSME

CVC

CVCA

RVCA

PDDR

PCA

PLA

PDAB

PIAB

OCTO

PRG

LINEAR ENCODER

MAXTUNE

DELTA

MITSUBISHI

TECHNOSOFT

PDAB-D3/D3T

- Ironless Linear Motor
- Peak force to 434N, Continuous force to 87N

PDAB SERIES IRONLESS LINEAR MOTOR

LINEAR ACTUATOR

DX B / BT

PIX / PIXA

PSM / PSME

CVC

CVCA

RVCA

PCB

PIAB

OCTO

PRG

LINEAR ENCODER

MAXTUNE

DELTA

MITSUBISHI

TECHNOSOFT

SPECIFICATION	Unit	MODEL							
		DX30B/BT							
		PDAB-D3-C1		PDAB-D3-C2		PDAB-D3T-C2		PDAB-D3-C3	
Motor Parameters	Unit	S	P	S	P	P	S	P	
Peak Force	N	145		289				434	
Continuous Force @ 120°C*	N	29		58				87	
Peak Power @ 120°C	W	695		1390				2086	
Continuous Power @ 120°C*	W	28		56				83	
Peak Current	A ^{pk}	11.81	23.63	11.81	23.63	47.25		11.81	23.63
Continuous Current @ 120°C*	A ^{pk}	2.36	4.73	2.36	4.73	9.45		2.36	4.73
Continuous Stall Current @ 120°C*	Arms	1.75	3.5	1.75	3.5	7		1.75	3.5
Force Constant	N/A ^{pk}	12.3	6.1	24.5	12.3	6.1		36.8	18.4
Back EMF Constant	V ^{pk} /m/s	14.1	7	28.2	14.1	7		42.3	21.1
Coil Resistance L-L @ 25°C	Ohm	4.8	1.2	9.6	2.4	0.6		14.4	3.6
Coil Resistance L-L @ 120°C*	Ohm	6.6	1.7	13.3	3.3	0.8		19.9	5
Inductance L-L @ 1kHz	mH	3	0.75	6	1.5	0.38		9	2.25
Motor Constant @ 25°C*	N/√W	6.46		9.13				11.18	
Motor Constant @ 120°C*	N/√W	5.49		7.76				9.51	
Max. Terminal Voltage	Vdc	400							
Thermal Resistance @ 120°C*	°C/W	3.42		1.71				1.14	
Max. Coil Temperature	°C	120							
Electrical Cycle Length	mm	60							

Specifications

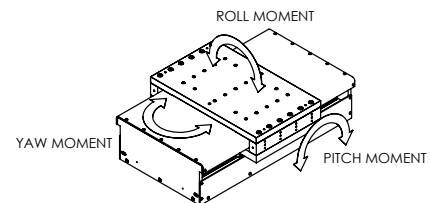
Repeatability**	um	±2.0							
Accuracy***	um	±20um/300mm							
Straightness***	um	±8um/300mm							
Flatness***	um	±8um/300mm							

Linear Guide Rated Load and Static Moment

Model Code		LM Guide							
Block Quantity		4							
Maximum bearing load	N	3125							
Pitch moment	Nm	104		191				287	
Yaw moment	Nm	104		191				287	
Roll moment	Nm	218							

Notes:

1. $A^{pk} = 1.414 \cdot Arms$; $V^{pk} = 1.414 \cdot Vrms$.
2. * Ambient temperature 25°C, heat dissipation by natural convection, without heat sink attached.
3. Specifications tolerance – inductance +/-30%, all others +/-10% (for motor parameters).
4. Peak force and current - 1 second duration.
5. ** Depend on encoder resolution.
6. *** Specific accuracy, straightness and flatness requirement, contact PBA for more information.
7. For customized stroke length, contact PBA.
8. For different motor models, contact PBA.



PDAB-D3/D3T

- Ironless Linear Motor
- Peak force to 724N, Continuous force to 145N

PDAB SERIES IRONLESS LINEAR MOTOR

SPECIFICATION		MODEL					
		DX30B/BT					
		PDAB-D3-C4		PDAB-D3T-C4		PDAB-D3-C5	
Motor Parameters	Unit	S	P	P	S	P	
Peak Force	N	579			724		
Continuous Force @ 120°C*	N	116			145		
Peak Power @ 120°C	W	2781			3476		
Continuous Power @ 120°C*	W	111			139		
Peak Current	A ^{pk}	11.81	23.63	47.25	11.81	23.63	
Continuous Current @ 120°C*	A ^{pk}	2.36	4.73	9.45	2.36	4.73	
Continuous Stall Current @ 120°C*	Arms	1.75	3.5	7	1.75	3.5	
Force Constant	N/A ^{pk}	49	24.5	12.3	61.3	30.6	
Back EMF Constant	V ^{pk} /m/s	56.4	28.2	14.1	70.4	35.2	
Coil Resistance L-L @ 25°C	Ohm	19.2	4.8	1.2	24	6	
Coil Resistance L-L @ 120°C*	Ohm	26.6	6.6	1.7	33.2	8.3	
Inductance L-L @ 1kHz	mH	12	3	0.75	15	3.75	
Motor Constant @ 25°C*	N/√W	12.91			14.44		
Motor Constant @ 120°C*	N/√W	10.98			12.27		
Max. Terminal Voltage	Vdc	400					
Thermal Resistance @ 120°C*	°C/W	0.85			0.68		
Max. Coil Temperature	°C	120					
Electrical Cycle Length	mm	60					

Specifications

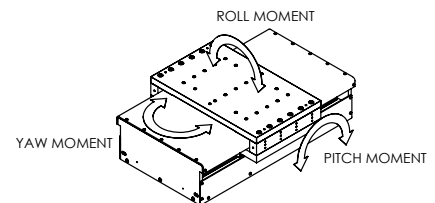
Repeatability**	um	±2.0
Accuracy***	um	±20um/300mm
Straightness***	um	±8um/300mm
Flatness***	um	±8um/300mm

Linear Guide Rated Load and Static Moment

Model Code		LM Guide
Block Quantity		4
Maximum bearing load	N	3125
Pitch moment	Nm	287
Yaw moment	Nm	287
Roll moment	Nm	218

Notes:

1. $A^{pk} = 1.414 * Arms$; $V^{pk} = 1.414 * Vrms$.
2. * Ambient temperature 25°C, heat dissipation by natural convection, without heat sink attached.
3. Specifications tolerance – inductance +/-30%, all others +/-10% (for motor parameters).
4. Peak force and current - 1 second duration.
5. ** Depend on encoder resolution.
6. *** Specific accuracy, straightness and flatness requirement, contact PBA for more information.
7. For customized stroke length, contact PBA.
8. For different motor models, contact PBA.



PDAB-D3/D3T (OPEN TYPE)

LINEAR ACTUATOR

DX B / BT

PIX / PIXA

PSM / PSME

CVC

CVCA

RVCA

PDDR

PCA

PLA

PDAB

PIAB

OCTO

PRG

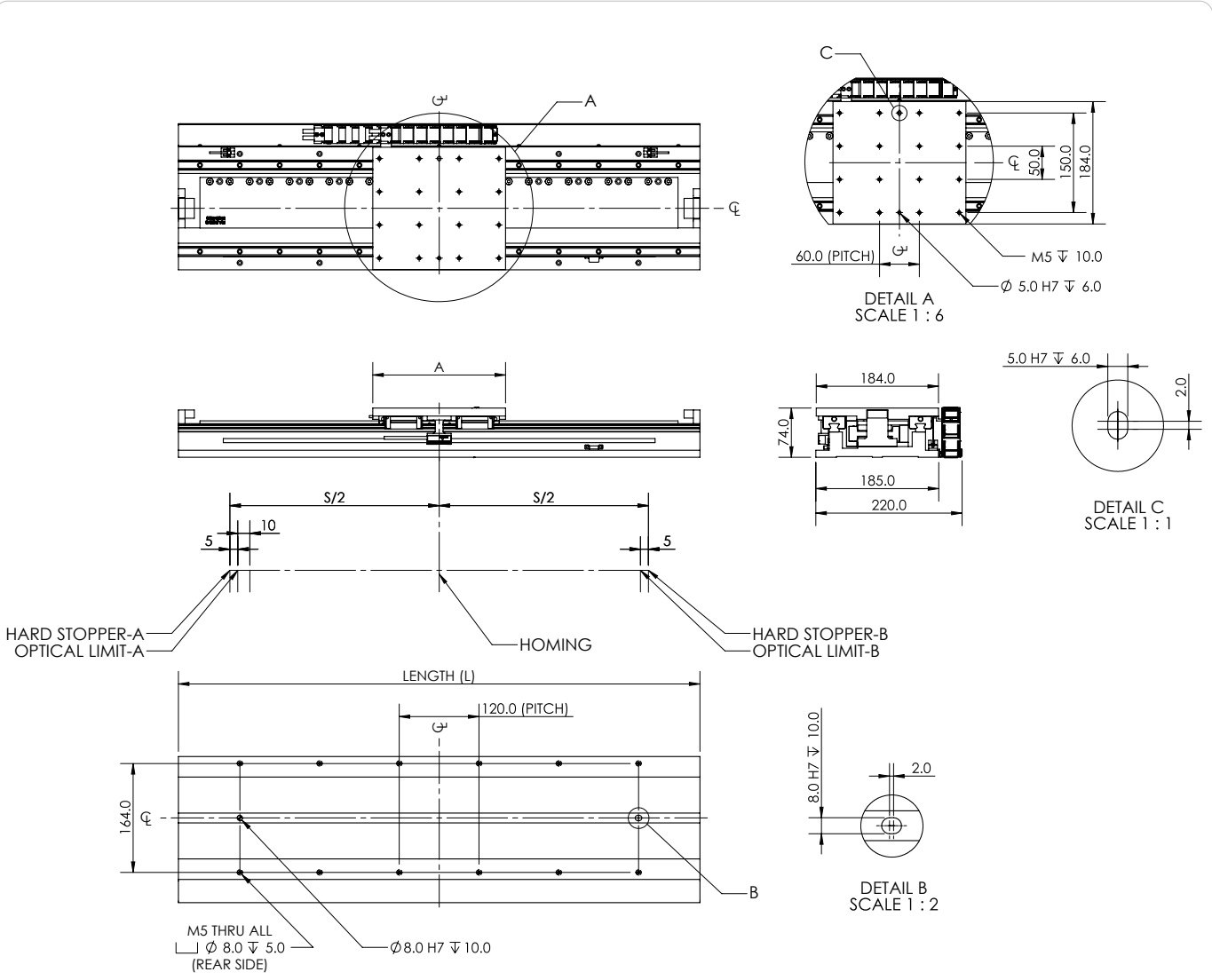
LINEAR ENCODER

MAXTUNE

DELTA

MITSUBISHI

TECHNOSOFT



MOTOR MODEL	STROKE (S) mm	ACTUATOR (L) mm	STROKE/ACTUATOR LENGTH (S) / (L) mm	CARRIAGE LENGTH (A) mm	SLIDER MASS kg	MODULE MASS (W) kg	
C1	MIN:100 MAX:1600	MIN : 225 MAX: 1725	S=100+(Multiple of 60mm) L=S+A+(65mm)	80	1.2	MIN : 5.1 MAX: 50.1	W=5.1 + (Multiple of 1.8kg)
C2		MIN : 285 MAX: 1785		140	1.6	MIN : 6.9 MAX: 51.9	W=6.9 + (Multiple of 1.8kg)
C3		MIN : 345 MAX: 1845		200	1.9	MIN : 8.7 MAX: 53.7	W=8.7 + (Multiple of 1.8kg)
C4		MIN : 405 MAX: 1905		260	2.3	MIN : 10.5 MAX: 55.5	W=10.5 + (Multiple of 1.8kg)
C5		MIN : 465 MAX: 1965		320	2.7	MIN : 12.3 MAX: 57.3	W=12.3 + (Multiple of 1.8kg)

- Notes:
- Slider Mass = Coil Mass + Carriage Mass
 - Module mass increment of 1.8kg per 60mm

PDAB-D3/D3T (COVERED TYPE)

LINEAR ACTUATOR

DX B / BT

PIX / PIXA

PSM / PSME

CVC

CVCA

RVCA

PDDR

PCA

PLA

PDAB

PIAB

OCTO

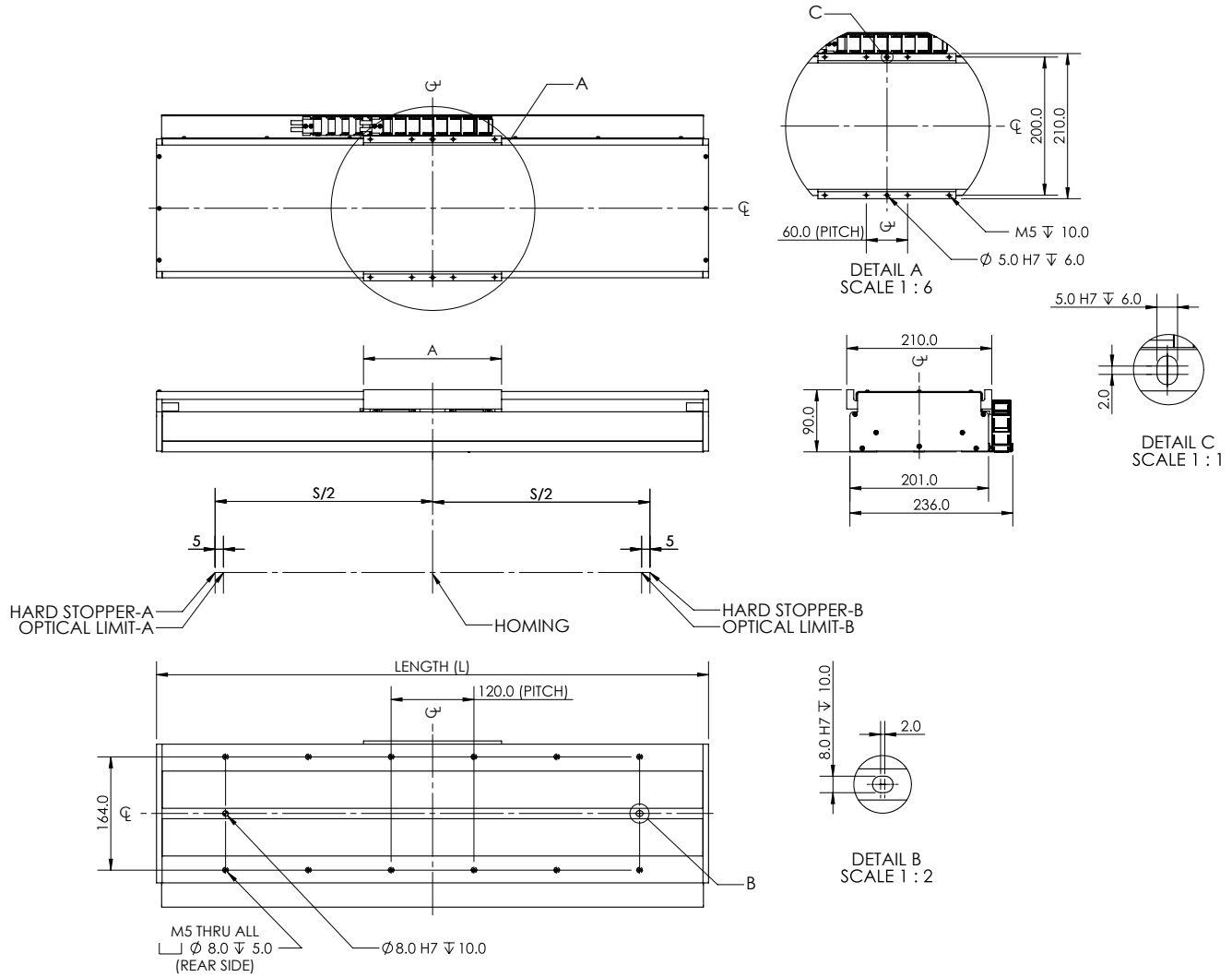
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LINEAR ENCODER

MAXTUNE

DELTA

TECHNOSOFT

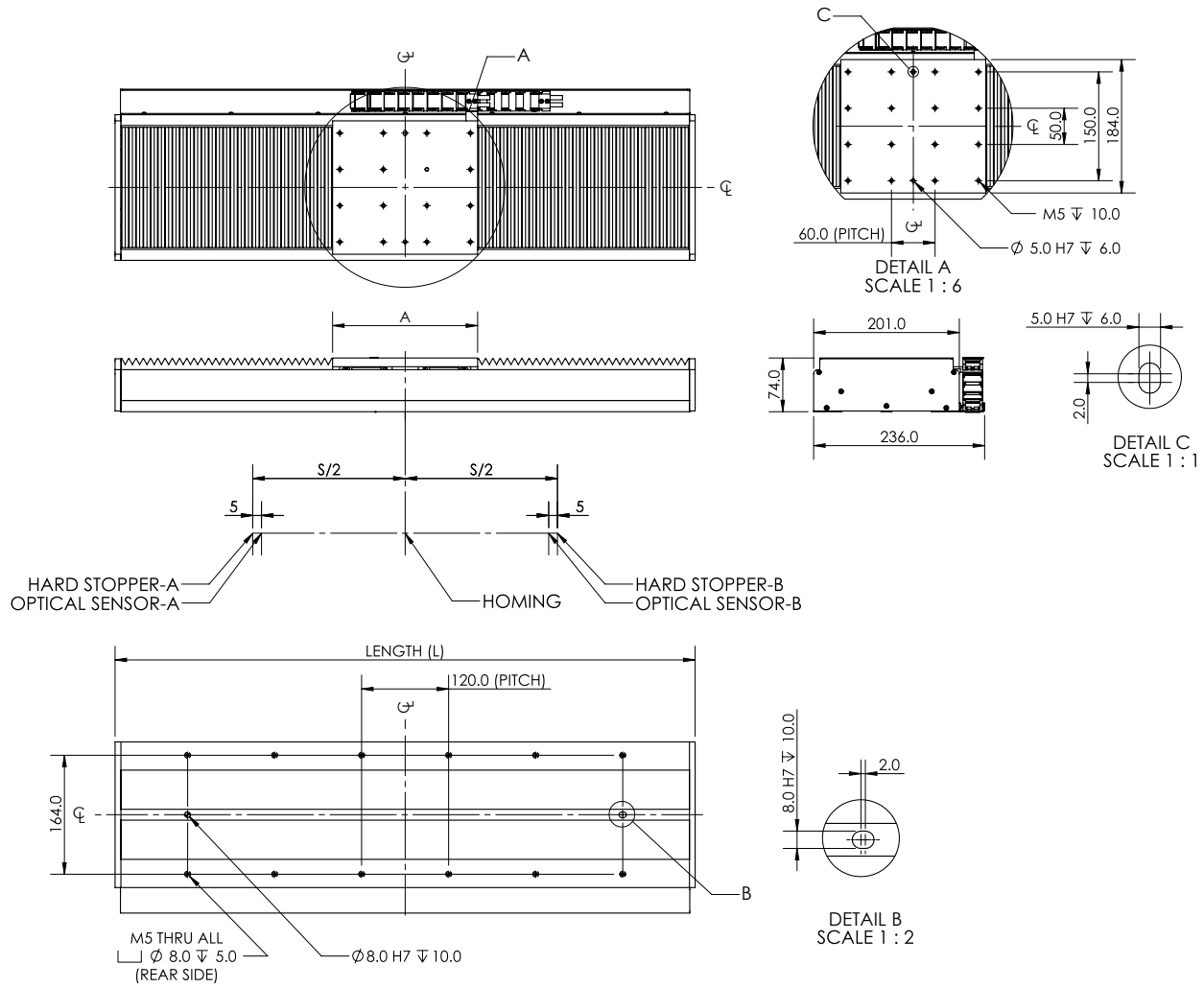


MOTOR MODEL	STROKE (S) mm	ACTUATOR (L) mm	STROKE/ACTUATOR LENGTH (S) / (L) mm	CARRIAGE LENGTH (A) mm	SLIDER MASS kg	MODULE MASS (W) kg	
C1	MIN:100 MAX:1600	MIN : 240 MAX: 1740	S=100+(Multiple of 60mm) L=S+A+(80mm)	80	1.4	MIN : 6.6 MAX: 61.6	W=6.6 + (Multiple of 2.2kg)
C2		MIN : 300 MAX: 1800		140	1.9	MIN : 8.8 MAX: 63.8	W=8.8 + (Multiple of 2.2kg)
C3		MIN : 360 MAX: 1860		200	2.3	MIN : 11.0 MAX: 66.0	W=11.0 + (Multiple of 2.2kg)
C4		MIN : 420 MAX: 1920		260	2.8	MIN : 13.2 MAX: 68.2	W=13.2 + (Multiple of 2.2kg)
C5		MIN : 480 MAX: 1980		320	3.3	MIN : 15.4 MAX: 70.4	W=15.4 + (Multiple of 2.2kg)

Notes:

- Slider Mass = Coil Mass + Carriage Mass
- Module mass increment of 2.2kg per 60mm

PDAB-D3/D3T (BELLOW TYPE)



MOTOR MODEL	STROKE (S) mm	ACTUATOR (L) mm	STROKE/ACTUATOR LENGTH (S) / (L) mm	CARRIAGE LENGTH (A) mm	SLIDER MASS kg	MODULE MASS (W) kg	
C1	MIN:100 MAX:1000	MIN : 300 MAX: 1650	S=100+(Multiple of 60mm) L=S+A+(170mm)	80	1.3	MIN : 7.6 MAX: 45.1	W=7.6 + (Multiple of 2.5kg)
C2		MIN : 360 MAX: 1710		140	1.6	MIN : 10.1 MAX: 47.6	W=10.1 + (Multiple of 2.5kg)
C3		MIN : 420 MAX: 1770		200	2.0	MIN : 12.6 MAX: 50.1	W=12.6 + (Multiple of 2.5kg)
C4		MIN : 480 MAX: 1830		260	2.4	MIN : 15.1 MAX: 52.6	W=15.1 + (Multiple of 2.5kg)
C5		MIN : 540 MAX: 1890		320	2.8	MIN : 17.6 MAX: 55.1	W=17.6 + (Multiple of 2.5kg)

Notes:

1. Slider Mass = Coil Mass + Carriage Mass
2. Module mass increment of 2.5kg per 60mm

LINEAR ACTUATOR

DX B / BT

PIX / PIXA

PSM / PSME

CVC

CVCA

RVCA

PDDR / PCA

PLA

PDAB

PIAB

OCTO

PRG

LINEAR ENCODER

MAXTUNE

DELTA

MITSUBISHI

TECHNOSOFT

PDAB-D5/D5T

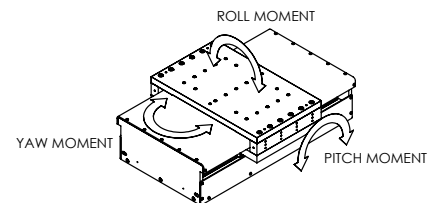
- Ironless Linear Motor
- Peak force to 446N, Continuous force to 89N

PDAB SERIES IRONLESS LINEAR MOTOR

SPECIFICATION		MODEL				
		DX50B/BT				
		PDAB-D5-C1		PDAB-D5-C2		PDAB-D5T-C2
Motor Parameters	Unit	S	P	S	P	P
Peak Force	N	223		446		
Continuous Force @ 120°C*	N	45		89		
Peak Power @ 120°C	W	751		1502		
Continuous Power @ 120°C*	W	30		60		
Peak Current	A ^{pk}	13.13	26.25	13.13	26.25	52.5
Continuous Current @ 120°C*	A ^{pk}	2.63	5.25	2.63	5.25	10.5
Continuous Stall Current @ 120°C*	Arms	2.1	4.2	2.1	4.2	8.4
Force Constant	N/A ^{pk}	17	8.5	34	17	8.5
Back EMF Constant	V ^{pk} /m/s	19.6	9.8	39.1	19.6	9.8
Coil Resistance L-L @ 25°C	Ohm	4.2	1.1	8.4	2.1	0.5
Coil Resistance L-L @ 120°C*	Ohm	5.8	1.5	11.6	2.9	0.7
Inductance L-L @ 1kHz	mH	3.11	0.78	6.22	1.56	0.39
Motor Constant @ 25°C*	N/√W	9.58		13.55		
Motor Constant @ 120°C*	N/√W	8.14		11.51		
Max. Terminal Voltage	V _{dc}	400				
Thermal Resistance @ 120°C*	°C/W	3.16		1.58		
Max. Coil Temperature	°C	120				
Electrical Cycle Length	mm	60				
Specifications						
Repeatability**	um	±2.0				
Accuracy***	um	±20um/300mm				
Straightness***	um	±8um/300mm				
Flatness***	um	±8um/300mm				
Linear Guide Rated Load and Static Moment						
Model Code		LM Guide				
Block Quantity		4				
Maximum bearing load	N	3125				
Pitch moment	Nm	104			191	
Yaw moment	Nm	104			191	
Roll moment	Nm	218				

Notes:

1. A^{pk} = 1.414 * Arms; V^{pk} = 1.414 * Vr_{ms}.
2. * Ambient temperature 25°C, heat dissipation by natural convection, without heat sink attached.
3. Specifications tolerance – inductance +/-30%, all others +/-10% (for motor parameters).
4. Peak force and current - 1 second duration.
5. ** Depend on encoder resolution.
6. *** Specific accuracy, straightness and flatness requirement, contact PBA for more information.
7. For customized stroke length, contact PBA.
8. For different motor models, contact PBA.



PDAB-D5/D5T

- Ironless Linear Motor
- Peak force to 116N, Continuous force to 223N

PDAB SERIES IRONLESS LINEAR MOTOR

LINEAR ACTUATOR

DX B / BT

PIX / PIXA

PSM / PSME

CVC

CVCA

RVCA

PDDR / PCA

PLA

PDAB

PIAB

OCTO

PRG

LINEAR ENCODER

MAXTUNE

DELTA

MITSUBISHI

TECHNOSOFT

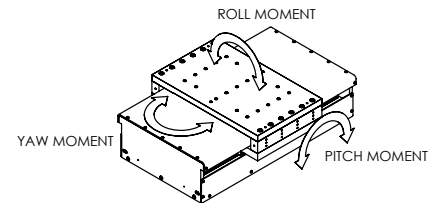
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		DX50B/BT							
		PDAB-D5-C3		PDAB-D5-C4		PDAB-D5T-C4		PDAB-D5-C5	
Motor Parameters	Unit	S	P	S	P	P	S	P	
Peak Force	N	669		893		1116			
Continuous Force @ 120°C*	N	134		179		223			
Peak Power @ 120°C	W	2253		3004		3755			
Continuous Power @ 120°C*	W	90		120		150			
Peak Current	A ^{pk}	13.13	26.25	13.13	26.25	52.5	13.13	26.25	
Continuous Current @ 120°C*	A ^{pk}	2.63	5.25	2.63	5.25	10.5	2.63	5.25	
Continuous Stall Current @ 120°C*	Arms	2.1	4.2	2.1	4.2	8.4	2.1	4.2	
Force Constant	N/A ^{pk}	51	25.5	68	34	17	85	42.5	
Back EMF Constant	V ^{pk} /m/s	58.7	29.3	78.2	39.1	19.6	97.8	48.9	
Coil Resistance L-L @ 25°C	Ohm	12.6	3.2	16.8	4.2	1.1	21	5.3	
Coil Resistance L-L @ 120°C*	Ohm	17.4	4.4	23.2	5.8	1.5	29.1	7.3	
Inductance L-L @ 1kHz	mH	9.33	2.33	12.44	3.11	0.78	15.55	3.89	
Motor Constant @ 25°C*	N/√W	16.59		19.16		21.42			
Motor Constant @ 120°C*	N/√W	14.1		16.28		18.21			
Max. Terminal Voltage	Vdc			400					
Thermal Resistance @ 120°C*	°C/W	1.05		0.79		0.63			
Max. Coil Temperature	°C			120					
Electrical Cycle Length	mm			60					

Specifications		
Repeatability**	um	±2.0
Accuracy***	um	±20um/300mm
Straightness***	um	±8um/300mm
Flatness***	um	±8um/300mm

Linear Guide Rated Load and Static Moment		
Model Code		LM Guide
Block Quantity		4
Maximum bearing load	N	3125
Pitch moment	Nm	287
Yaw moment	Nm	287
Roll moment	Nm	218

Notes:

1. $A^{pk} = 1.414 \cdot Arms$; $V^{pk} = 1.414 \cdot V_{rms}$.
2. * Ambient temperature 25°C, heat dissipation by natural convection, without heat sink attached.
3. Specifications tolerance – inductance +/-30%, all others +/-10% (for motor parameters).
4. Peak force and current - 1 second duration.
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PDAB-D5/D5T (OPEN TYPE)

LINEAR ACTUATOR

DX / B / BT

PIX / PIXA

PSM / PSME

CVC

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PDAB

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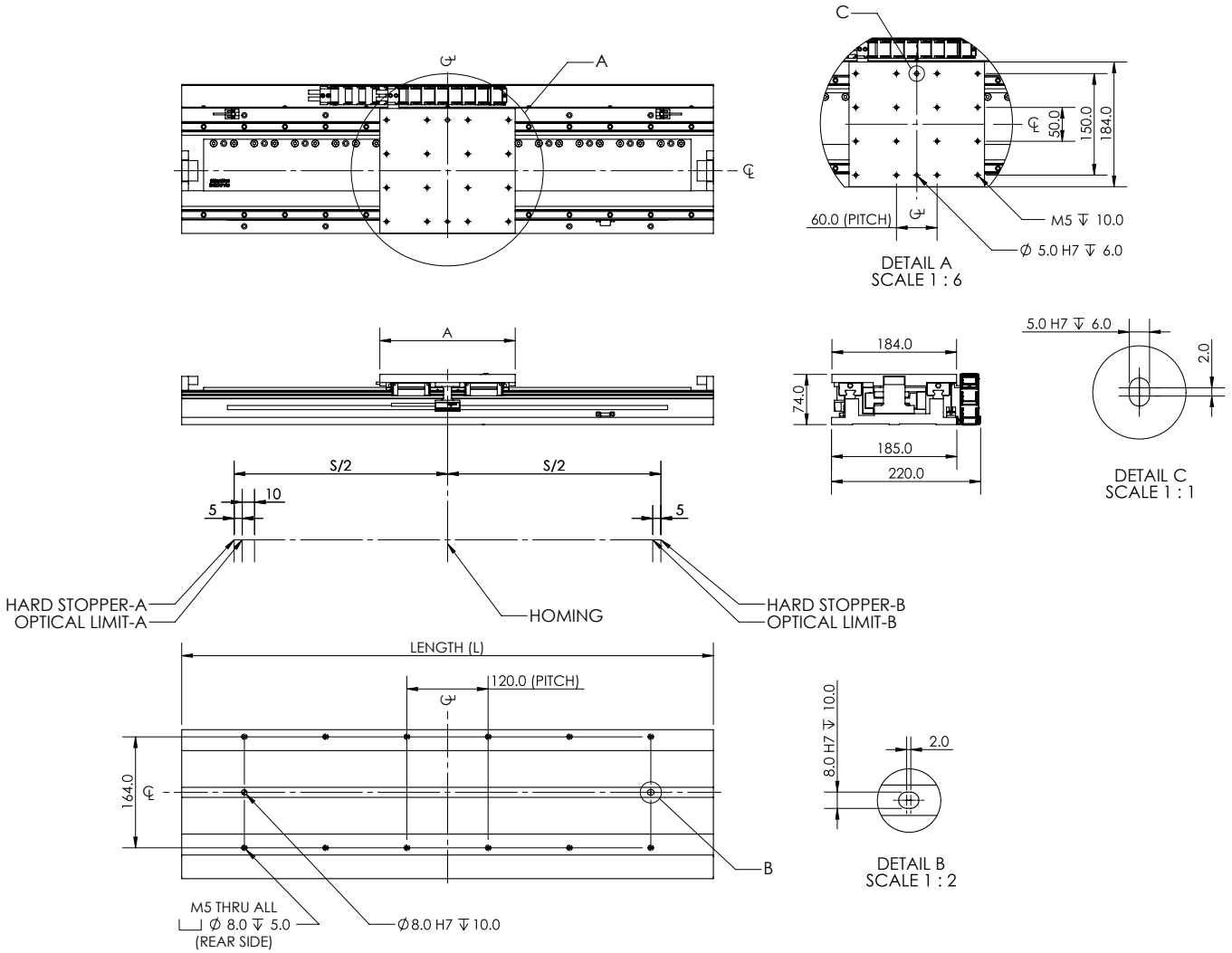
LINEAR ENCODER

MAXTUNE

DELTA

MITSUBISHI

TECHNOSOFT



MOTOR MODEL	STROKE (S) mm	ACTUATOR (L) mm	STROKE/ACTUATOR LENGTH (S) / (L) mm	CARRIAGE LENGTH (A) mm	SLIDER MASS kg	MODULE MASS (W) kg	
C1	MIN:100 MAX:1600	MIN : 225 MAX: 1725	S=100+(Multiple of 60mm) L=S+A+(65mm)	80	1.3	MIN : 6.0 MAX: 58.5	W=6.0 + (Multiple of 2.1kg)
C2		MIN : 285 MAX: 1785		140	1.7	MIN : 8.1 MAX: 60.6	W=8.1 + (Multiple of 2.1kg)
C3		MIN : 345 MAX: 1845		200	2.1	MIN : 10.2 MAX: 62.7	W=10.2 + (Multiple of 2.1kg)
C4		MIN : 405 MAX: 1905		260	2.5	MIN : 12.3 MAX: 64.8	W=12.3 + (Multiple of 2.1kg)
C5		MIN : 465 MAX: 1965		320	2.9	MIN : 14.4 MAX: 66.9	W=14.4 + (Multiple of 2.1kg)

Notes:

1. Slider Mass = Coil Mass + Carriage Mass
2. Module mass increment of 2.1kg per 60mm

PDAB-D5/D5T (COVERED TYPE)

LINEAR ACTUATOR

DX B / BT

PIX / PIXA

PSM / PSME

CVC

CVCA

RVCA

PDDR

PCA

PLA

PDAB

PIAB

OCTO

PRG

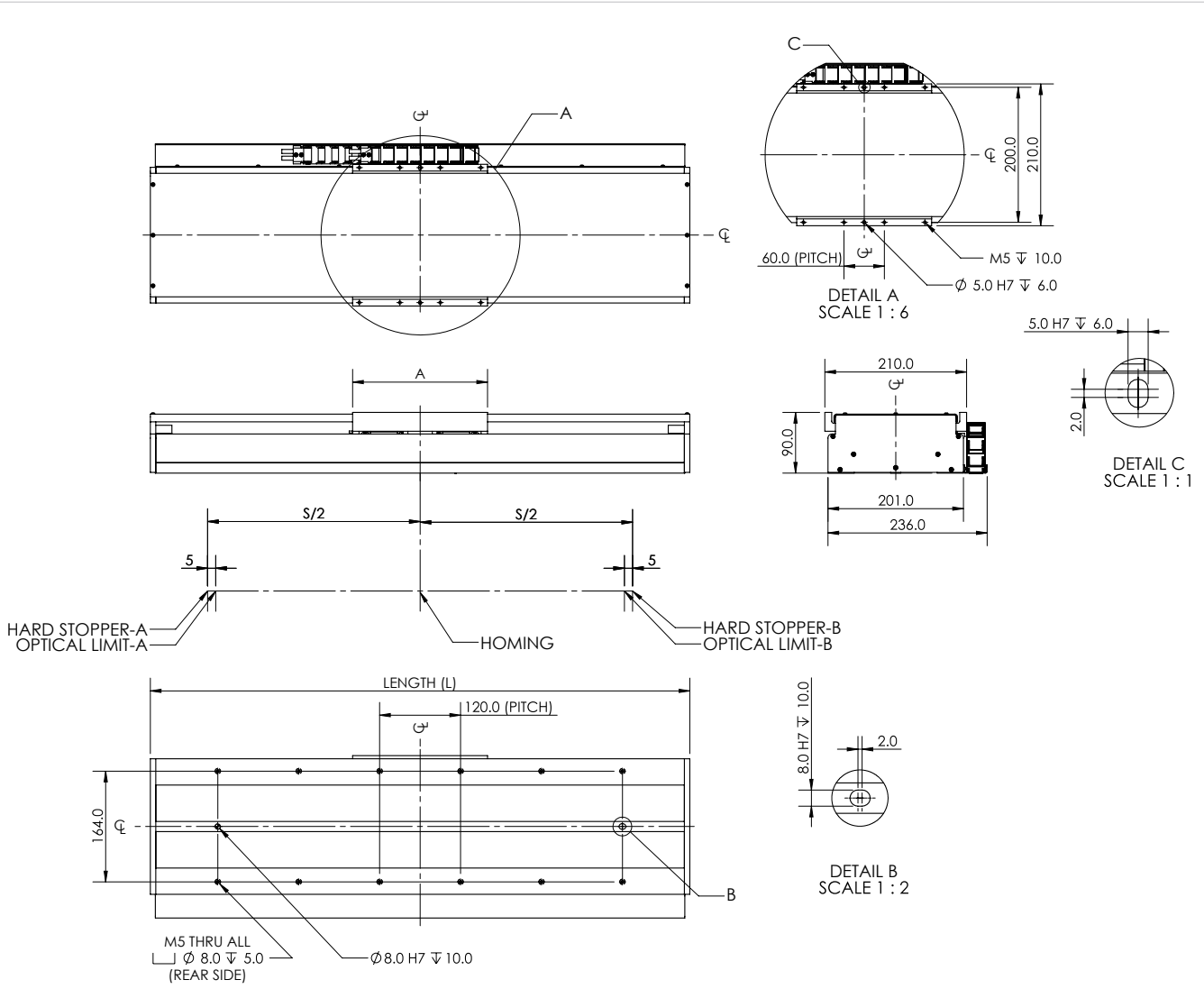
LINEAR ENCODER

MAXTUNE

DELTA

MITSUBISHI

TECHNOSOFT



MOTOR MODEL	STROKE (S) mm	ACTUATOR (L) mm	STROKE/ACTUATOR LENGTH (S) / (L) mm	CARRIAGE LENGTH (A) mm	SLIDER MASS kg	MODULE MASS (W) kg	
C1	MIN:100 MAX:1600	MIN : 240 MAX: 1740	S=100+(Multiple of 60mm) L=S+A+(80mm)	80	1.5	MIN : 7.5 MAX: 70.0	W=6.6 + (Multiple of 2.5kg)
C2		MIN : 300 MAX: 1800		140	2.0	MIN : 10.0 MAX: 72.5	W=8.8 + (Multiple of 2.5kg)
C3		MIN : 360 MAX: 1860		200	2.5	MIN : 12.5 MAX: 75.0	W=11.0 + (Multiple of 2.5kg)
C4		MIN : 420 MAX: 1920		260	3.0	MIN : 15.0 MAX: 77.5	W=13.2 + (Multiple of 2.5kg)
C5		MIN : 480 MAX: 1980		320	3.5	MIN : 17.5 MAX: 80.0	W=15.4 + (Multiple of 2.5kg)

Notes:
 1. Slider Mass = Coil Mass + Carriage Mass
 2. Module mass increment of 2.5kg per 60mm

PDAB-D5/D5T (BELLOW TYPE)

LINEAR ACTUATOR

DX B / BT

PIX / PIXA

PSM / PSME

CVC

CVCA

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PCA

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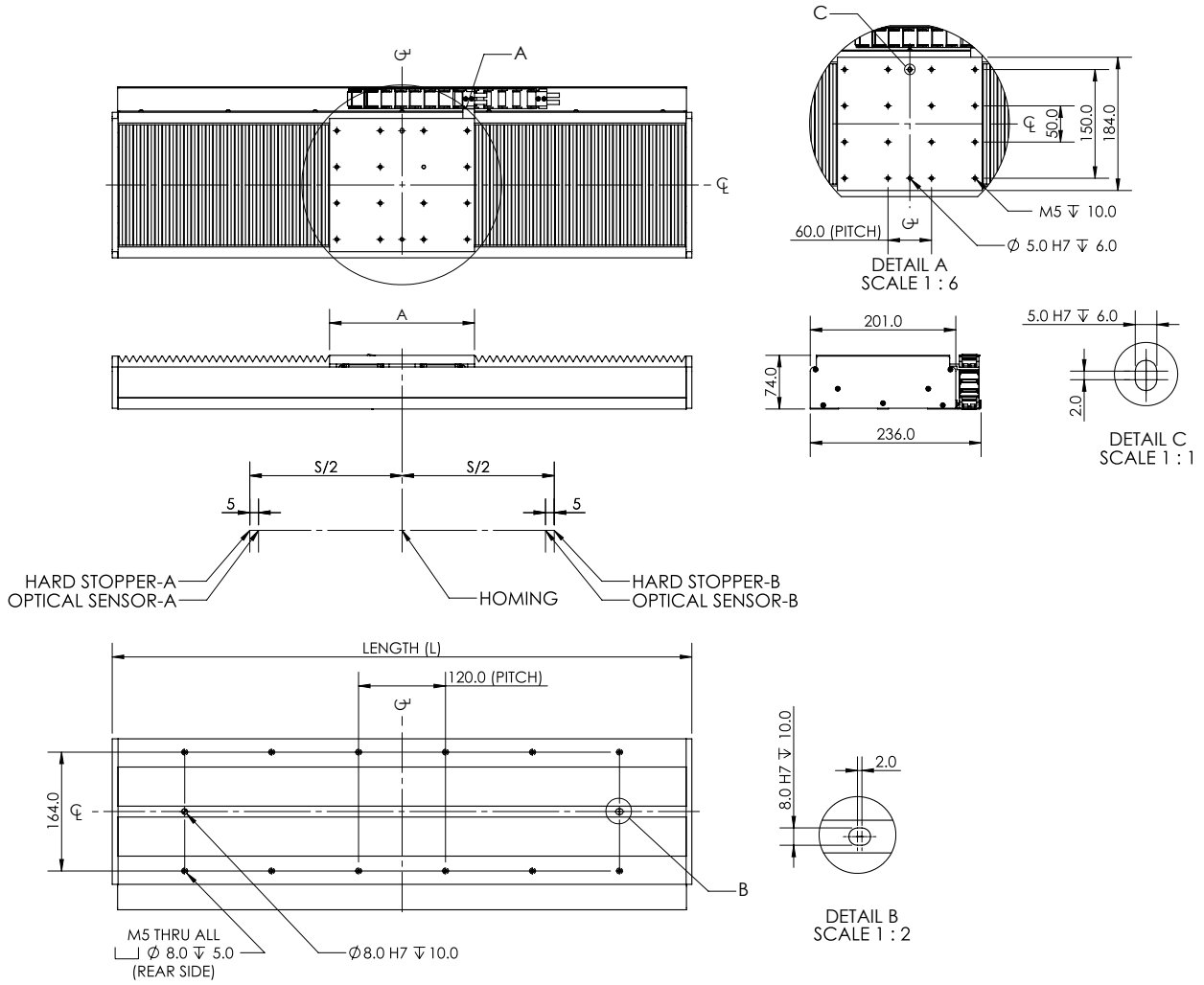
LINEAR ENCODER

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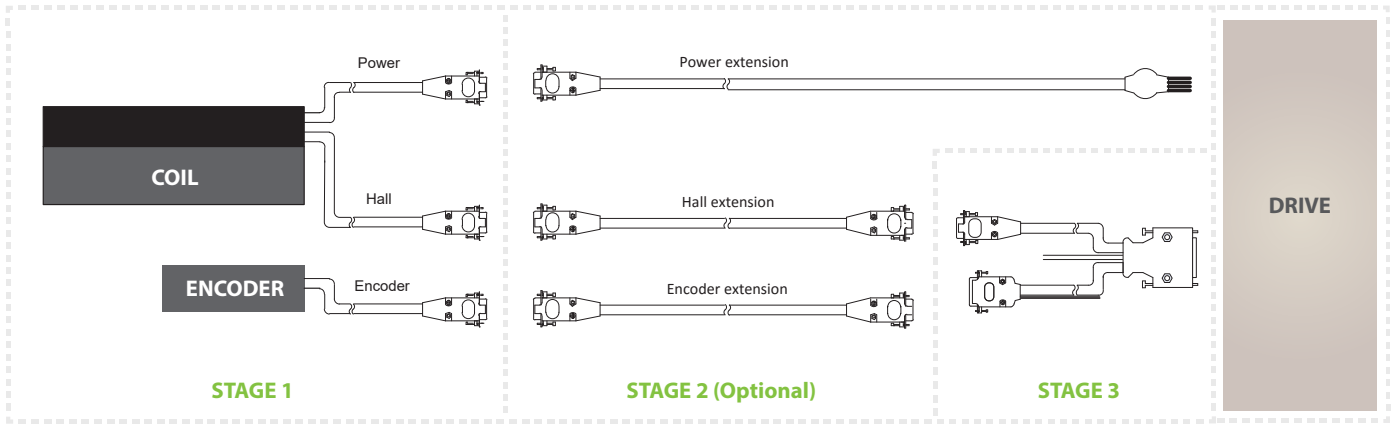


MOTOR MODEL	STROKE (S) mm	ACTUATOR (L) mm	STROKE/ACTUATOR LENGTH (S) / (L) mm	CARRIAGE (A) mm	SLIDER MASS kg	MODULE MASS (W) kg	
C1	MIN:100 MAX:1000	MIN : 300 MAX: 1650	S=100+(Multiple of 60mm) L=S+A+(170mm)	80	1.4	MIN : 8.5 MAX: 50.5	W=8.5 + (Multiple of 2.8kg)
C2		MIN : 360 MAX: 1710		140	1.7	MIN : 11.3 MAX: 53.3	W=11.3 + (Multiple of 2.8kg)
C3		MIN : 420 MAX: 1770		200	2.2	MIN : 14.1 MAX: 56.1	W=14.1 + (Multiple of 2.8kg)
C4		MIN : 480 MAX: 1830		260	2.6	MIN : 16.9 MAX: 58.9	W=16.9 + (Multiple of 2.8kg)
C5		MIN : 540 MAX: 1890		320	3.0	MIN : 19.7 MAX: 61.7	W=19.7 + (Multiple of 2.8kg)

Notes:

1. Slider Mass = Coil Mass + Carriage Mass
2. Module mass increment of 2.8kg per 60mm

CABLE OPTION



STAGE 1

POWER AND HALL CABLE OPTION

PDAB-D5-C1-S-TM-1.0-FC-HC-E1.0-O-1600-00

POWER CABLE OPTIONS																													
NF		<table border="1"> <tr><td>M1</td><td>Pink & Yellow</td></tr> <tr><td>M2</td><td>Green & Blue</td></tr> <tr><td>M3</td><td>Brown & Black</td></tr> <tr><td>PE</td><td>Yellow</td></tr> <tr><td>Temp sensor 1</td><td>Orange / Black</td></tr> <tr><td>Temp sensor 2</td><td>Orange</td></tr> </table>	M1	Pink & Yellow	M2	Green & Blue	M3	Brown & Black	PE	Yellow	Temp sensor 1	Orange / Black	Temp sensor 2	Orange															
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HALL SENSOR OPTIONS																	
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CHC	 Push Pull 5 Pin Male	<table border="1"> <tr><td>P1</td><td>Hall A</td><td>White</td></tr> <tr><td>P2</td><td>Hall B</td><td>Green</td></tr> <tr><td>P3</td><td>Hall C</td><td>Blue</td></tr> <tr><td>P4</td><td>5V</td><td>Red</td></tr> <tr><td>P5</td><td>0V</td><td>Black</td></tr> </table>	P1	Hall A	White	P2	Hall B	Green	P3	Hall C	Blue	P4	5V	Red	P5	0V	Black
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The temperature in which the thermostat is active is shown as below:

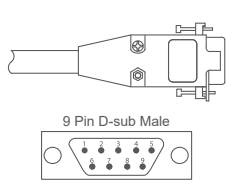
MODEL	THERMAL DEVICE TYPE	THERMOSTAT (NC) OPENS AT
DX 30B	PT100	See Note 1
DX 30B	Thermostat	100°C
DX 50B	Thermostat	100°C

Note 1

- Programmable on temperature controller or analog inputs on motion controller.
- Recommended to set cut-off temperature to 100°C (max) to prevent coil damage.
- User has to ensure that the thermal protection devices are wired to appropriate electronics to ensure that the motor power cutoff is active when temperature reaches its allowable limit.

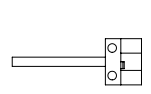
PDAB CABLE PIN OUT

ENCODER CONNECTOR - 9 PIN D-SUB MALE



	RH200X / RH200Z	RH200B
P1	0V DC	0V DC
P2	A+	Sine+
P3	Z+	Z+
P4	B+	Cosine+
P5	+5V DC	+5V DC
P6	A-	Sine-
P7	Z-	Z-
P8	B-	Cosine-
P9	Inner	Inner
Casing	Outer	Outer

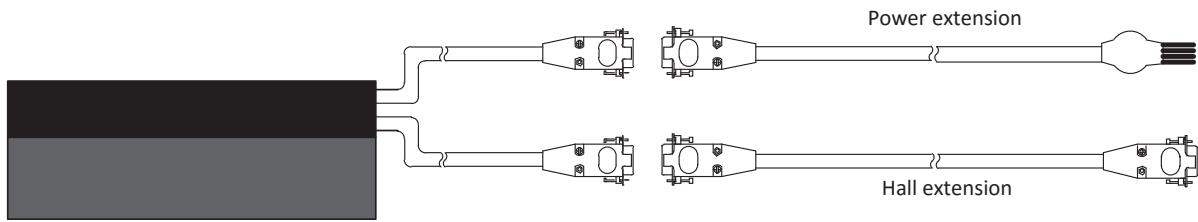
OPTICAL LIMIT SWITCH (PM-L24)

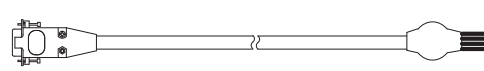
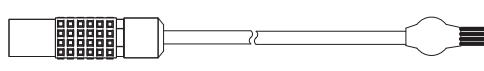
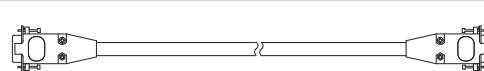
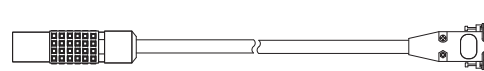



+5V dc	Brown
GND	Blue
LIGHT-ON	Black
DARK-ON	White

STAGE 2 PDAB EXTENSION CABLE

Connection example: PDAB-D5-C1-S-TM-1.0-FC-HC-E1.0-O-1600-00



	Extension Cable	Part Number									
Power Extension Cable		CBL_EXT_PWR_DX_X.X									
		CBL_EXT_PWR_DX_CC_X.X									
Hall Sensor Extension Cable		CBL_EXT_HALL_DX_X.X									
		CBL_EXT_HALL_DX_CC_X.X									
Encoder Extension Cable		CBL_EXT_REN01_X.X									
	<table border="1"> <thead> <tr> <th>CABLE</th> <th>CABLE LENGTH (X.X)</th> </tr> </thead> <tbody> <tr> <td>01 RH200 Digital</td> <td>0.5 0.5 meter</td> </tr> <tr> <td rowspan="5">01B RH200 Analog</td> <td>1.0 1.0 meter</td> </tr> <tr> <td>2.0 2.0 meter</td> </tr> <tr> <td>3.0 3.0 meter</td> </tr> <tr> <td>4.0 4.0 meter</td> </tr> <tr> <td>5.0 5.0 meter</td> </tr> </tbody> </table>	CABLE	CABLE LENGTH (X.X)	01 RH200 Digital	0.5 0.5 meter	01B RH200 Analog	1.0 1.0 meter	2.0 2.0 meter	3.0 3.0 meter	4.0 4.0 meter	5.0 5.0 meter
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Notes: 1. X.X is the length of the cable in meters 2. For customized cable length, contact PBA